

Related rates [20 marks]

A water trough which is 10 metres long has a uniform cross-section in the shape of a semicircle with radius 0.5 metres. It is partly filled with water as shown in the following diagram of the cross-section. The centre of the circle is O and the angle KOL is θ radians.

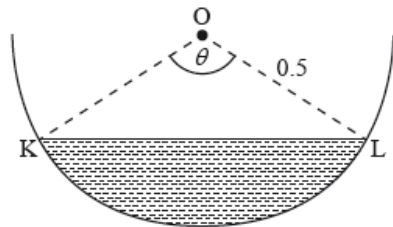


diagram not to scale

- 1a. Find an expression for the volume of water V (m^3) in the trough in terms of θ . [3 marks]

Markscheme

* This question is from an exam for a previous syllabus, and may contain minor differences in marking or structure.

$$\text{area of segment} = \frac{1}{2} \times 0.5^2 \times (\theta - \sin \theta) \quad \mathbf{M1A1}$$

$$V = \text{area of segment} \times 10$$

$$V = \frac{5}{4}(\theta - \sin \theta) \quad \mathbf{A1}$$

[3 marks]

The volume of water is increasing at a constant rate of $0.0008\text{m}^3\text{s}^{-1}$.

- 1b. Calculate $\frac{d\theta}{dt}$ when $\theta = \frac{\pi}{3}$. [4 marks]

Markscheme

METHOD 1

$$\frac{dV}{dt} = \frac{5}{4}(1 - \cos \theta) \frac{d\theta}{dt} \quad \mathbf{M1A1}$$

$$0.0008 = \frac{5}{4}(1 - \cos \frac{\pi}{3}) \frac{d\theta}{dt} \quad \mathbf{(M1)}$$

$$\frac{d\theta}{dt} = 0.00128 \text{ (rad s}^{-1}\text{)} \quad \mathbf{A1}$$

METHOD 2

$$\frac{d\theta}{dt} = \frac{d\theta}{dV} \times \frac{dV}{dt} \quad \mathbf{(M1)}$$

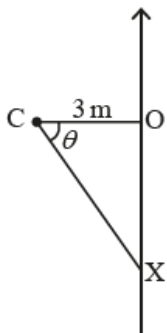
$$\frac{dV}{d\theta} = \frac{5}{4}(1 - \cos \theta) \quad \mathbf{A1}$$

$$\frac{d\theta}{dt} = \frac{4 \times 0.0008}{5(1 - \cos \frac{\pi}{3})} \quad \mathbf{(M1)}$$

$$\frac{d\theta}{dt} = 0.00128 \left(\frac{4}{3125} \right) \text{ (rad s}^{-1}\text{)} \quad \mathbf{A1}$$

[4 marks]

2. A camera at point C is 3 m from the edge of a straight section of road as [6 marks] shown in the following diagram. The camera detects a car travelling along the road at $t = 0$. It then rotates, always pointing at the car, until the car passes O, the point on the edge of the road closest to the camera.



A car travels along the road at a speed of 24 ms^{-1} . Let the position of the car be X and let $\text{OCX} = \theta$.

Find $\frac{d\theta}{dt}$, the rate of rotation of the camera, in radians per second, at the instant the car passes the point O.

Markscheme

* This question is from an exam for a previous syllabus, and may contain minor differences in marking or structure.

let $OX = x$

METHOD 1

$$\frac{dx}{dt} = 24 \quad (\text{or } -24) \quad \mathbf{(A1)}$$

$$\frac{d\theta}{dt} = \frac{dx}{dt} \times \frac{d\theta}{dx} \quad \mathbf{(M1)}$$

$$3 \tan \theta = x \quad \mathbf{A1}$$

EITHER

$$3 \sec^2 \theta = \frac{dx}{d\theta} \quad \mathbf{A1}$$

$$\frac{d\theta}{dt} = \frac{24}{3 \sec^2 \theta}$$

attempt to substitute for $\theta = 0$ into their differential equation $\mathbf{M1}$

OR

$$\theta = \arctan\left(\frac{x}{3}\right)$$

$$\frac{d\theta}{dx} = \frac{1}{3} \times \frac{1}{1 + \frac{x^2}{9}} \quad \mathbf{A1}$$

$$\frac{d\theta}{dt} = 24 \times \frac{1}{3\left(1 + \frac{x^2}{9}\right)}$$

attempt to substitute for $x = 0$ into their differential equation $\mathbf{M1}$

THEN

$$\frac{d\theta}{dt} = \frac{24}{3} = 8 \quad (\text{rad s}^{-1}) \quad \mathbf{A1}$$

Note: Accept -8 rad s^{-1} .

METHOD 2

$$\frac{dx}{dt} = 24 \quad (\text{or } -24) \quad \mathbf{(A1)}$$

$$3 \tan \theta = x \quad \mathbf{A1}$$

attempt to differentiate implicitly with respect to t $\mathbf{M1}$

$$3 \sec^2 \theta \times \frac{d\theta}{dt} = \frac{dx}{dt} \quad \mathbf{A1}$$

$$\frac{d\theta}{dt} = \frac{24}{3 \sec^2 \theta}$$

attempt to substitute for $\theta = 0$ into their differential equation $\mathbf{M1}$

$$\frac{d\theta}{dt} = \frac{24}{3} = 8 \quad (\text{rad s}^{-1}) \quad \mathbf{A1}$$

Note: Accept -8 rad s^{-1} .

Note: Can be done by consideration of CX, use of Pythagoras.

METHOD 3

let the position of the car be at time t be $d - 24t$ from O **(A1)**

$$\tan \theta = \frac{d-24t}{3} \left(= \frac{d}{3} - 8t \right) \quad \mathbf{M1}$$

Note: For $\tan \theta = \frac{24t}{3}$ award **A0M1** and follow through.

EITHER

attempt to differentiate implicitly with respect to t **M1**

$$\sec^2 \theta \frac{d\theta}{dt} = -8 \quad \mathbf{A1}$$

attempt to substitute for $\theta = 0$ into their differential equation **M1**

OR

$$\theta = \arctan \left(\frac{d}{3} - 8t \right) \quad \mathbf{M1}$$

$$\frac{d\theta}{dt} = \frac{8}{1 + \left(\frac{d}{3} - 8t \right)^2} \quad \mathbf{A1}$$

$$\text{at O, } t = \frac{d}{24} \quad \mathbf{A1}$$

THEN

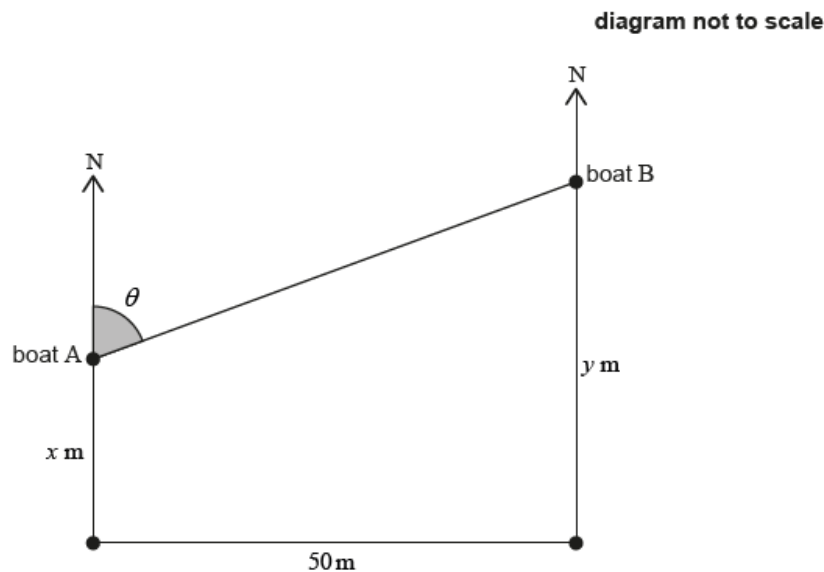
$$\frac{d\theta}{dt} = -8 \quad \mathbf{A1}$$

[6 marks]

Two boats A and B travel due north.

Initially, boat B is positioned 50 metres due east of boat A.

The distances travelled by boat A and boat B, after t seconds, are x metres and y metres respectively. The angle θ is the radian measure of the bearing of boat B from boat A. This information is shown on the following diagram.



3a. Show that $y = x + 50 \cot \theta$.

[1 mark]

Markscheme

$$\tan \theta = \frac{50}{y-x} \text{ OR } \cot \theta = \frac{y-x}{50} \text{ A1}$$

$$y = x + 50 \cot \theta \text{ AG}$$

Note: $y - x$ may be identified as a length on a diagram, and not written explicitly.

[1 mark]

3b. At time T , the following conditions are true.

[6 marks]

Boat B has travelled 10 metres further than boat A.

Boat B is travelling at double the speed of boat A.

The rate of change of the angle θ is -0.1 radians per second.

Find the speed of boat A at time T .

Markscheme

attempt to differentiate with respect to t **(M1)**

$$\frac{dy}{dt} = \frac{dx}{dt} - 50(\operatorname{cosec} \theta)^2 \frac{d\theta}{dt} \text{ **A1**}$$

attempt to set speed of B equal to double the speed of A **(M1)**

$$2 \frac{dx}{dt} = \frac{dx}{dt} - 50(\operatorname{cosec} \theta)^2 \frac{d\theta}{dt}$$

$$\frac{dx}{dt} = -50(\operatorname{cosec} \theta)^2 \frac{d\theta}{dt} \text{ **A1**}$$

$\theta = \arctan 5 (= 1.373\dots = 78.69\dots^\circ)$ OR

$$\operatorname{cosec}^2 \theta = 1 + \cot^2 \theta = 1 + \left(\frac{1}{5}\right)^2 = \frac{26}{25} \text{ **(A1)**}$$

Note: This **A1** can be awarded independently of previous marks.

$$\frac{dx}{dt} = -50\left(\frac{26}{25}\right) \times -0.1$$

So the speed of boat A is $5.2 \text{ (ms}^{-1}\text{)}$ **A1**

Note: Accept 5.20 from the use of inexact values.

[6 marks]